

Talk to D-Bus from a Python application



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Brussels, 2023

D-Bus

protocol - bus daemon - inter-process

System Bus

Session Bus



chat

org.example.Chat

activatable: no, pid: 15920, cmd: python3 examples/05_chat/s

org.hexchat.service

activatable: yes, pid: 7934, cmd: hexchat --existing

Address: unix:path=/run/user/1000/bus

Name: org.example.Chat

Unique name: :1.214

Object path

- ▶ /org/example/Chat
- ▶ /org/example/Chat/Rooms/1
- ▶ /org/example/Chat/Rooms/2
- ▼ /org/example/Chat/Rooms/3
 - ▼ Interfaces
 - ▼ org.example.Chat.Room
 - ▼ Methods
 - SendMessage (String msg) → ()
 - ▼ Properties
 - String Name (read)
 - ▼ Signals
 - MessageReceived (String)
 - ▶ org.freedesktop.DBus.Introspectable
 - ▶ org.freedesktop.DBus.Peer
 - ▶ org.freedesktop.DBus.Properties

dasbus library

Python - GLib - D-Bus

Part 1: Client

Create a D-Bus proxy

Specify the
D-Bus name
of the service
and D-Bus
path of the
object.

```
bus = SessionMessageBus()  
proxy = bus.get_proxy(  
    "org.example.Chat",  
    "/org/example/Chat/Rooms/3"  
)
```

Get a D-Bus property

Get a property of the D-Bus proxy.

```
print(proxy.Name)
```

Call a D-Bus method

Call a method of the D-Bus proxy.

```
proxy.SendMessage("Hello World!")
```


Watch a D-Bus signal

Connect a
callback to the
signal of the
D-Bus proxy
and start the
event loop.

```
def callback(message):  
    print(message)  
  
proxy.MessageReceived.connect(  
    callback  
)
```

Run the event loop

Process
asynchronous
communication.

```
loop = EventLoop()  
loop.run()
```

Part 2: Service

Register a D-Bus service

Specify a
D-Bus name
of the service.

```
bus = SessionMessageBus()  
bus.register_service(  
    "org.example.Chat"  
)
```

Publish a D-Bus object

Specify the
D-Bus path of
the object.

```
bus.publish_object(  
    "/org/example/Chat/Rooms/3",  
    Room()  
)
```

Start the event loop

Start to handle incoming D-Bus calls.

```
loop = EventLoop()  
loop.run()
```

Part 3: Object

XML Specification

```
<?xml version="1.0" ?>
```

```
<node>
```

```
  <interface name="org.example.Chat.Room">
```

```
    <method name="SendMessage">
```

```
      <arg direction="in" type="s"/>
```

```
    </method>
```

```
  </interface>
```

```
</node>
```


Generate the XML

Use a
decorator to
generate the
XML.

```
@dbus_interface("org.example.Chat.Room")  
class Room(object):
```

Define a D-Bus method

Use type hints
to define
types.

```
def SendMessage(self, msg: Str):  
    print(msg)
```

Define a D-Bus property

Use type hints to define types.

```
@property  
def Name(self) -> Str:  
    return "Room 3"
```

Define a D-Bus signal

Specify the
arguments
and types.

```
@dbus_signal
def MessageReceived(self, msg: Str):
    pass
```

Part 4: Features

Manage D-Bus names

Pre-define
D-Bus names
and paths of
services,
objects and
interfaces.

```
proxy = CHAT.get_proxy(ROOM_3)
```

Generate D-Bus paths

Manage a
group of
publishable
objects.

```
path = ROOM_CONTAINER.to_object_path(  
    room  
)
```

Handle D-Bus errors

Map names of D-Bus errors to exceptions.

```
try:  
    proxy.SendMessage(...)  
except ChatError:  
    ...
```


Handle D-Bus structures

Represent dictionaries of variants by Python objects.

```
data = UserData.from_structure(  
    structure  
)  
print(data.name)
```

Use Unix file descriptors

Send and receive Unix file descriptors.

```
proxy = bus.get_proxy(  
    ...  
    client=GLibClientUnix  
)
```

I don't need X

Features are optional.

I need Z

Classes are replaceable.

[https://github.com/
rhinstaller/dasbus](https://github.com/rhinstaller/dasbus)