FOSS on Mobile Devices - Camera BoF

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Hello, I'm Jacopo

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Hello, I'm Jacopo

• Linux camera engineer

- libcamera
- V4L2 camera driver



- The image capture pipeline
- The 3A loop
- A taxonomy of camera systems
- The complex camera interface
- The case for a camera stack



The image capture pipeline

It all starts with light beams being converted into electric signals





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Electrical information captured by the image sensor represents color channels in the RAW Bayer pattern of the sensor





The Bayer pattern gets 'debayered' and converted into a known color space





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Electrical information are manipulated in both analog and digital domains, with a large number of correction and enhancement techniques

- Defective pixel correction
- Lens shading
- Black level correction
- ... you name it



A long way to reach the final image

- Cropping or sub-sampling applied on the image sensor pixel array
- Cropping or re-scaling in the digital domain
- Rotation/flipping/mirroring etc
- Color format conversion (eg RAW-to-YVV)
- Color space conversions (RGB-to-YUV)
- Packaging and compression (JPEG, DNF etc)



Image capture is a closed-loop system





Image capture is a closed-loop system



ISP Image Signal Processor



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Image capture is a closed-loop system



3A loop



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A taxonomy of camera systems

Designs with a smart sensor









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• User visible functionalities depends on the selected sensor



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- Sensor are (still) programmed through binary blobs
- Vendor lock-in
- Higher BOM costs



Designs with an ISP





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• The SoC usually runs Linux



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• The SoC usually runs Linux

• The code that controls the ISP is potentially accessible



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• Features and performances



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• Features and performances

- High speed interconnects, higher clock rates
- Extended features set



• Higher chances of code re-use and standardization



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Higher chances of code re-use and standardization

• Reusable 3A algorithms



• Higher chances of code re-use and standardization

- Reusable 3A algorithms
- Open HW designs



The single devnode abstraction



The media controller abstraction





Why so complex ??



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The single devnode abstraction





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The single devnode abstraction





The media controller abstraction

{1080p, NV12}





The media controller abstraction

{1080p, NV12}





The media controller abstraction

{1080p, NV12}





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The media controller abstraction

{1080p, NV12}





Complex cameras

• User-space has to configure precisely each point in the pipeline



Complex cameras

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- An operating system should enable use cases, not hard-code them



Complex cameras

- User-space has to configure precisely each point in the pipeline
- An operating system should enable use cases, not hard-code them
- Platform-dependent configuration that has to be applied to the system to realize the desired use case



Applications got stuck

- Regular desktop application (Cheese): UVC cameras
- Gstreamer is the most common way to interface with cameras
- On embedded systems the 'system configuration' is usually a collection of scripts







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• Isolate device-specific components



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• Isolate device-specific components

- A camera pipeline handler is hardware support
- Vendor should ideally provide one as part of their BSPs
- To get them on-board quite some critical mass is needed



• Provide a generic API and a standardized set of controls to applications



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• Provide a generic API and a standardized set of controls to applications

- Abstract away platform specific details
- Adaption layers: gstreamer, Android Camera3, V4L2 emulation



• Library of 3A algorithms



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• Library of 3A algorithms

- Framework for open source implementations to compete with proprietary ones
- State of the art: Raspberry Pi IPA library



Does this apply to FOSS mobile devices too?



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Thank you for your attention

I hope you will enjoy the rest of the discussion



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