

Never

Functional Programming Language

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Agenda

Introduction

Motivation

Design

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Features

Demo

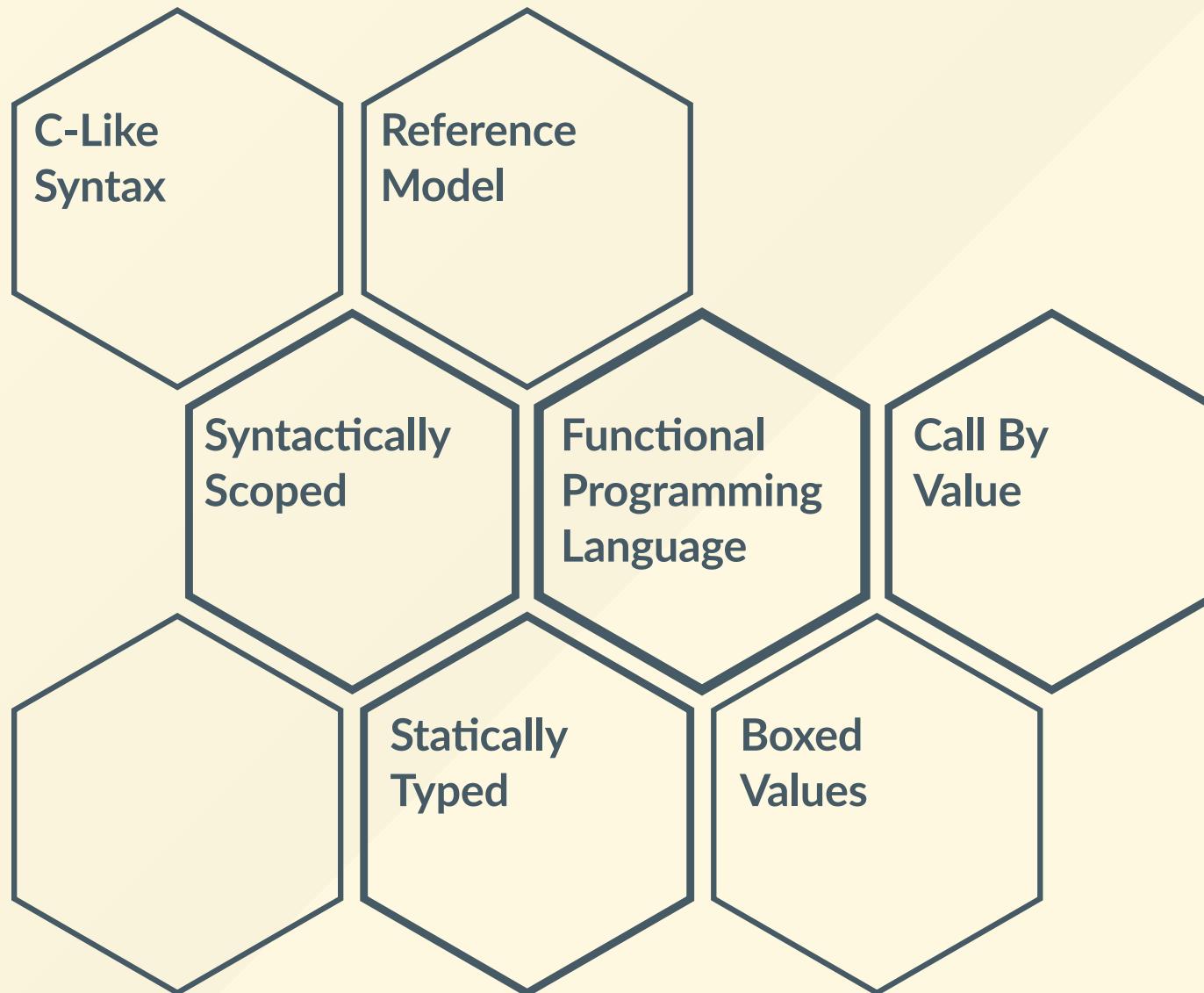
Neural Network | Perceptron
Supervised Learning | Results

Mary
PonyAgda
HugoZebraEulerAda
RainerOrwellPanda
TuringKarel
MirandaMercury
LisaCharityGödel
LilyFjölnirJulia
DogAlicePascalPike
EuclidBertrand
MonkeyEuphoriaMouse
LynxPythonEstrelKittenBS
KCybilHermesSwiftC
ReiaMirahViperQ
Hope

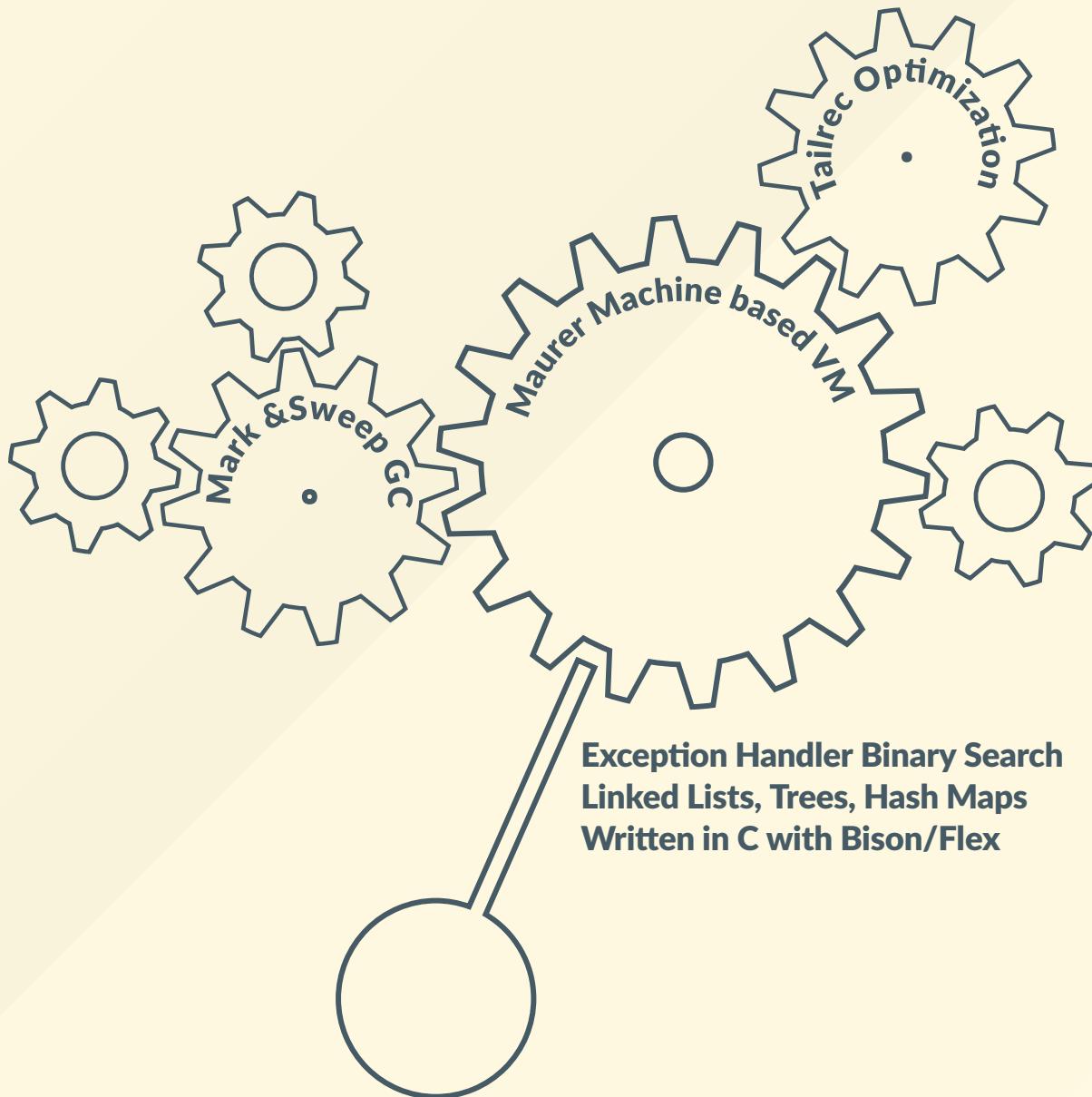
About Never

- Hobby project
- Creativity escape
- I wanted to learn more about programming languages
- Scripting languages are good for prototyping
- I chose matrices as they are frequently used in science and technology

Design Decisions



Under the Hood



Tick - Control - Functions & Expressions

```
func calc() -> (float) -> float {  
    func fah2cel(float f) -> float { (f - 32.0) / 1.8 }  
}  
  
func main() -> float {  
    calc()(212.0)  
}
```

- First class functions
- Everything is an expression
- Operators + - * / ?:
- Float

Tock - Types - Integer

```
func gcd(x -> int, y -> int) -> int {  
    (y == 0) ? x : gcd(y, x % y)  
}  
  
func main() -> int {  
    gcd(56, 12)  
}
```

- Integer
- Operator %
- Operators and or not

Tick - Control - Built-in

```
func deg2rad(deg -> float) -> float {
    deg * 3.14159 / 180
}

func get_func() -> (float) -> float {
    cos
}

func main() -> float {
    get_func()(deg2rad(60.0))
}
```

- Built-in functions:
 - sin, cos, tan, exp, log, sqrt, pow
 - print, printf, assert

Tock - Types - Matrices

```
func rotate_matrix(alpha -> float) -> [_,_] -> float {
    [ [ cos(alpha), -sin(alpha) ],
      [ sin(alpha), cos(alpha) ] ] -> float
}

func main() -> int {
    var vect = [[ 10.0, 0.0 ]] -> float;

    print_vect(vect * rotate_matrix(0.0));
}
```

- First class matrices
- Conformat arrays
- Overloaded operators + - *

Tick - Control Flow

```
var i = 0; var j = 0;

for ({ i = 0; j = 0 }; i < 10;
      { i = i + 1; j = j + 2 }) {
    print(i + j)
}
```

- Bindings
- Control flow
- Side effects
- Operator =

Tock - Types - String

```
func main() -> int {
    var s1 = "text equal";
    var s2 = "text equal";

    assert(if (s1 == s2) { 1 } else { 0 } == 1)
}
```

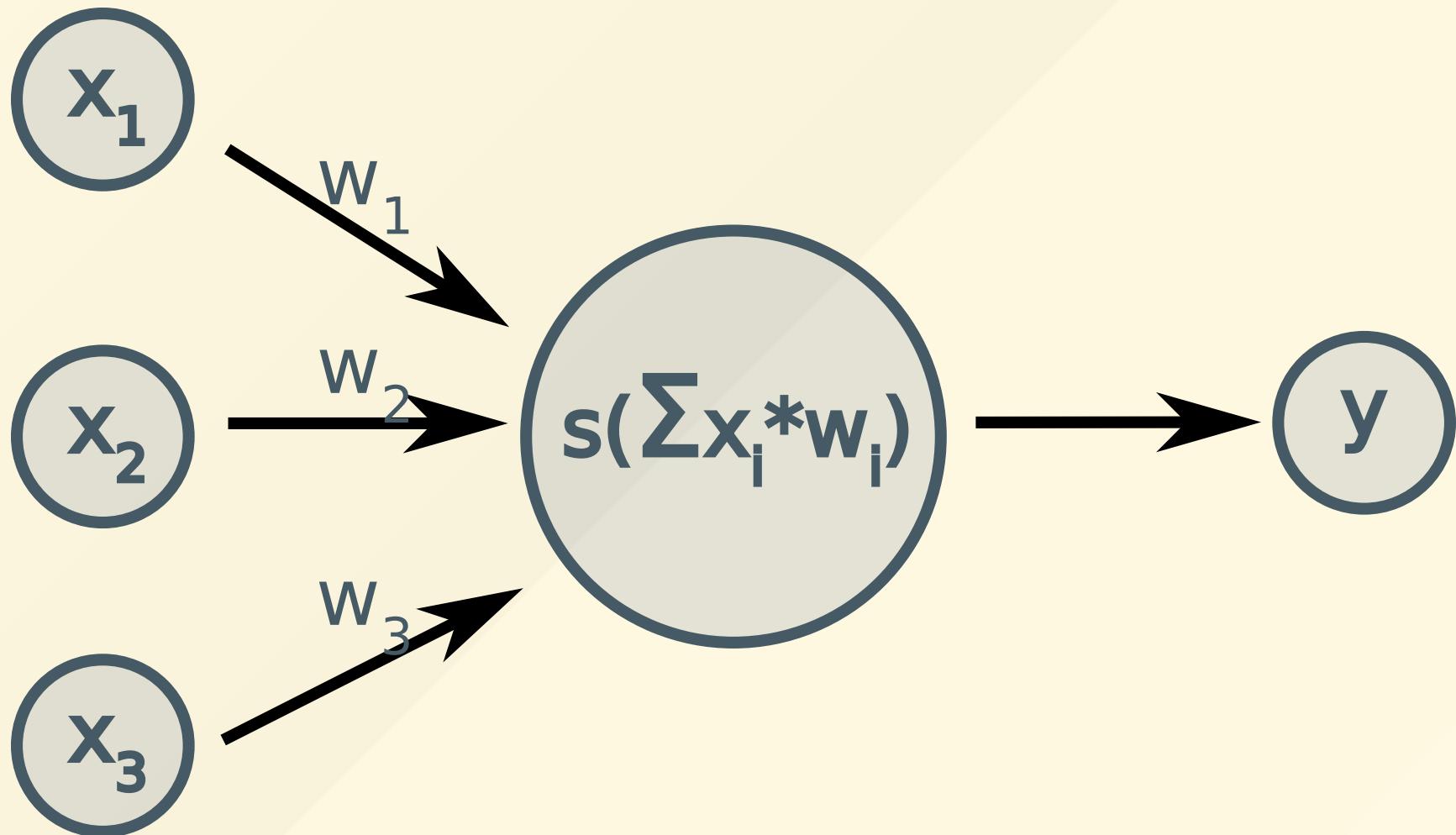
- Strings
- Operator == !=

Tick - Control - Exceptions

```
func one(d -> int) -> int {
    var f = let func (d -> int) -> int {
        12 / d
    }
    catch (division_by_zero)
    {
        12
    };
    f(0)
}
```

- Exceptions

Neural Network in Never



Sigmoid

```
func sigmoid(x -> float) -> float
{
    1.0 / (1.0 + exp(-x))
}
```

- Function $\frac{1}{1+e^{-x}}$
- Statically typed
- Float type
- Returns expression

Linear Congruential Generator

```
func randomize(seed -> int) -> () -> int
{
    var v = seed;
    func rand() -> int {
        v = (v * 1103515245 + 12345) % 2147483648
    }
    rand
}
```

- First class functions - `rand`
- Syntax scope - nested to any level
- `v` - closed within `randomize`

Matrix Algebra

```
func Hadamard_matrix(W1[D1, D2] -> float,
                      W2[D3, D4] -> float) -> [_,_] -> float
{
    var r = 0; var c = 0;
    var H = {[ D1, D2 ]} -> float;

    for (r = 0; r < D1; r = r + 1) {
        for (c = 0; c < D2; c = c + 1) {
            H[r, c] = W1[r, c] * W2[r, c]
        }
    };
    H
}
```

- Hadamard multiplication
- Conformant matrices (arrays)

Forward Propagation - Input & Output

```
var x = [ [0, 1, 0],  
          [1, 0, 0],  
          [1, 1, 1],  
          [0, 0, 1] ] -> float;  
  
var y = [ [1, 0, 1, 0] ] -> float;  
var yT = T_matrix(y);
```

- Input matrix x
- Output transposed matrix
 $y = [[1], [0], [1], [0]]$
- Middle value as output

Forward Propagation - Initialization

```
var W = {[ 3, 1 ]} -> float;  
var rand = randomize(165);  
  
rand_matrix(W, rand);
```

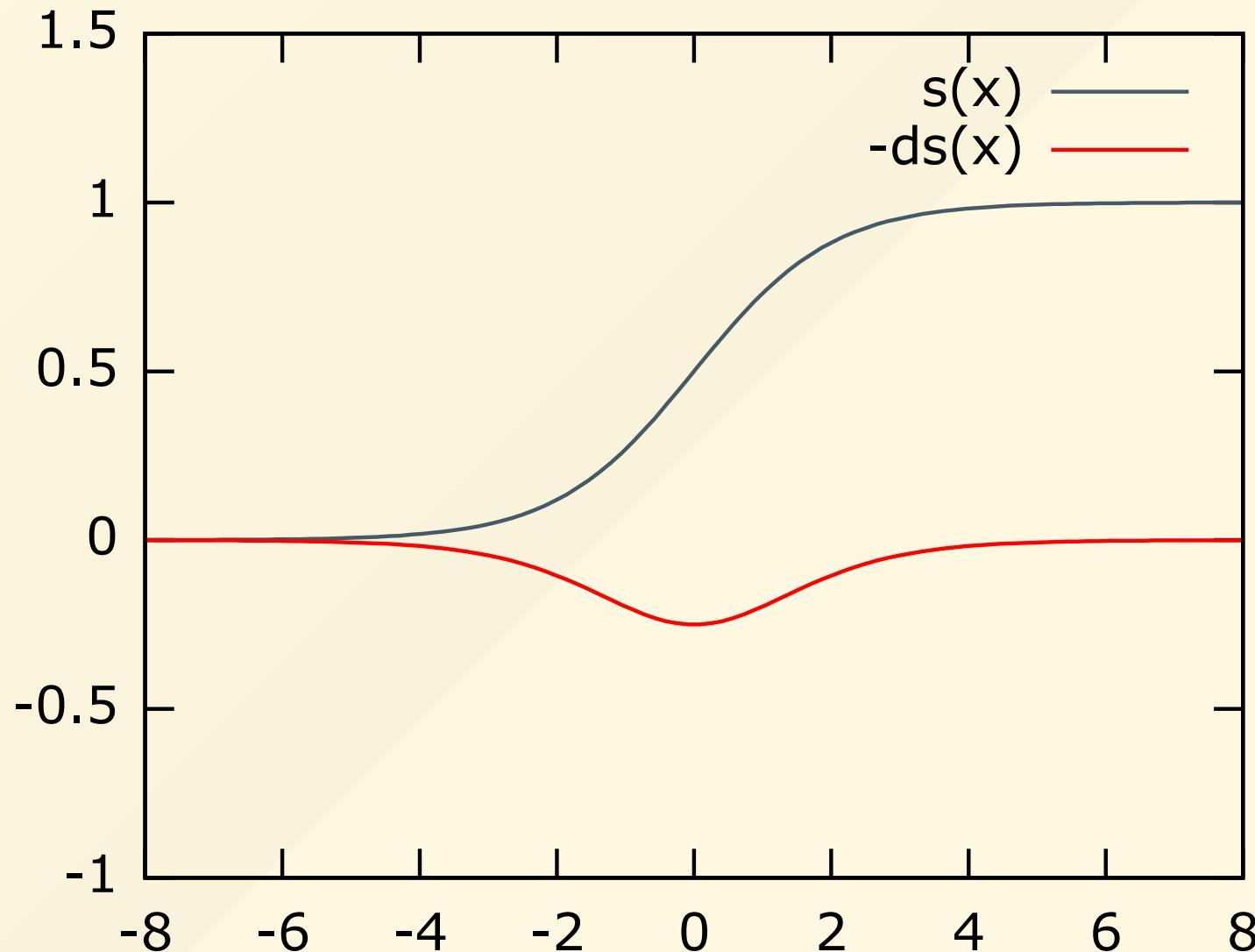
- **W** initialized to random values

Forward Propagation - Output Calculation

```
var s = {[ 4, 1 ]} -> float;  
  
s = sigmoid_matrix(x * W);
```

- Operators `+, -, *` are overloaded for matrices
- Output calculated to all inputs
- Sigmoid function used to get 0/1 results

Backpropagation - Error Reduction



Backpropagation - Error Calculation

```
var err = {[ 4, 1 ]} -> float;  
  
err = yT - s;
```

- Calculate error for each input sample
- `err` used to correct `w` weights

Backpropagation - Gradient Descent

```
var sD = {[ 4, 1 ]} -> float;  
var one = {[ 4, 1 ]} -> float;  
  
sD = Hadamard_matrix(s, one - s);  
W = W + xT * Hadamard_matrix(err, sD)
```

- $sD = s * (1 - s)$
- $W = W + xT * err * sD$
- First derivative (or gradient) multiplied by error lets to move towards function minimum
- Calculations for all input values x at once

Forward and Backpropagation Learning Cycles

```
func main() -> int {  
    var i = 0;  
    for (i = 0; i < 1000; i = i + 1) {  
        ...  
    }  
}
```

- Forward and backpropagation need to be repeated until error is low
- Function `main` as program entry point

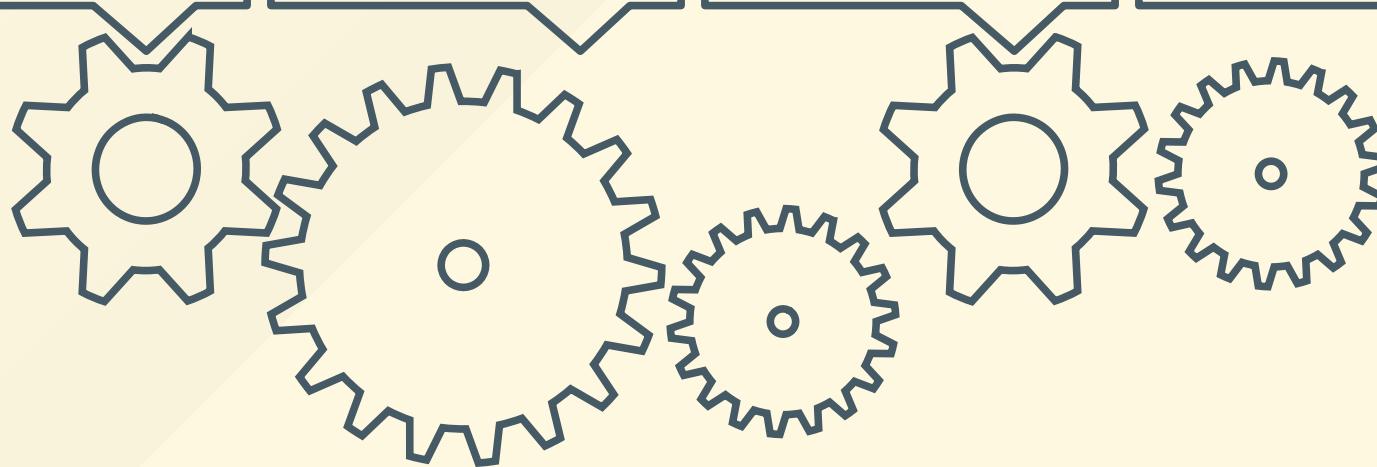
Results

X	s(X * W)	y
[[1, 1, 1]]	0.96	1.00
[[1, 1, 0]]	1.00	1.00
[[1, 0, 1]]	0.00	0.00
[[1, 0, 0]]	0.05	0.00
[[0, 1, 1]]	1.00	1.00
[[0, 1, 0]]	1.00	1.00
[[0, 0, 1]]	0.05	0.00
[[0, 0, 0]]	0.50	0.00

- 7 correct results, 1 undecided

Future

Types	Lists	Externals	Runtime
record polynomial functions type inference	join slice comprehension	I/O modules foreign function interface	libraries VM optimizations



Summary

- Creating programming languages...
 - is fun 😊
 - can teach you a lot 😅
 - is satisfactory 😎

Thank You!

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★ Star me!

73